
**Pneumatic fluid power — Electro-
pneumatic pressure control valves —**

Part 2:

**Test methods to determine main
characteristics to include in the
supplier's literature**

*Transmissions pneumatiques — Appareils électropneumatiques de
distribution à commande continue de pression —*

*Partie 2: Méthodes d'essai pour déterminer les principales
caractéristiques à inclure dans la documentation des fournisseurs*



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Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

The procedures used to develop this document and those intended for its further maintenance are described in the ISO/IEC Directives, Part 1. In particular, the different approval criteria needed for the different types of ISO documents should be noted. This document was drafted in accordance with the editorial rules of the ISO/IEC Directives, Part 2 (see www.iso.org/directives).

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. ISO shall not be held responsible for identifying any or all such patent rights. Details of any patent rights identified during the development of the document will be in the Introduction and/or on the ISO list of patent declarations received (see www.iso.org/patents).

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For an explanation of the voluntary nature of standards, the meaning of ISO specific terms and expressions related to conformity assessment, as well as information about ISO's adherence to the World Trade Organization (WTO) principles in the Technical Barriers to Trade (TBT), see www.iso.org/iso/foreword.html.

This document was prepared by Technical Committee ISO/TC 131, *Fluid power systems*, Subcommittee SC 5, *Control products and components*.

This second edition cancels and replaces the first edition (ISO 10094-2:2010), which has been technically revised.

The main changes are as follows:

- Addition of definitions for response time, settling time, and shifting time in [Clause 3](#);
- Revision of the procedure for the repeatability test: addition of 15 % and 85 % of the electrical control signal full scale to tested values (in addition to 50 %) in [7.2.4](#);
- Addition of two subclauses relating to Sensitivity ([7.3.7](#)) and Offset ([7.3.8](#)) respectively;
- Revision of the test procedure to determine leakage characteristics to simplify the test practice ([10.2](#));
- Deletion of the no tank test version and test circuit from the test practices in [Clause 11](#) related to dynamic characteristics;
- The former [subclause 11.2](#), frequency characteristics, has been made an informative annex ([Annex A](#)).

A list of all parts in the ISO 10094 series can be found on the ISO website.

Any feedback or questions on this document should be directed to the user's national standards body. A complete listing of these bodies can be found at www.iso.org/members.html.

Introduction

In pneumatic fluid power systems, power is transmitted and controlled through a gas under pressure within a circuit.

When pressure tracking or pressure regulation is required, electro-pneumatic continuous pressure control valves can be used to track a variable set point with low tracking error or to maintain the pressure of the gas at an approximately constant level.

These control valves continuously modulate the pneumatic pressure of a system in response to a continuous electrical input signal and link the electrical input value to a proportional pressure value.

It is therefore necessary to know some performance characteristics of these electro-pneumatic continuous pressure control valves in order to determine their suitability.

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Pneumatic fluid power — Electro-pneumatic pressure control valves —

Part 2:

Test methods to determine main characteristics to include in the supplier's literature

1 Scope

This document specifies the test procedures and a method of presenting results concerning the parameters which define the main characteristics to be included in the supplier's literature of the electro-pneumatic continuous pressure control valves, conforming to ISO 10094-1.

The purpose of this document is:

- to facilitate comparison by standardizing the test methods and the presentation of the test results, and
- to assist in the proper application of these components in compressed air systems.

The specified tests are intended to allow comparison between the different types of continuous pressure control valves; these are not production tests to be carried out on each manufactured product.

The tests described in this document are for components with an exhaust port vented to the atmosphere.

NOTE 1 The tests related to non-electrically modulated pneumatic continuous pressure control valves are specified in ISO 6953-2.

NOTE 2 The tests related to electro-pneumatic continuous flow control valves are specified in ISO 10041-2.

NOTE 3 ISO 6953-3 provides an alternate dynamic test method for flow-rate characteristics using an isothermal tank instead of a flow meter. However, this method measures only the decreasing flow rate part of the hysteresis curve of the forward flow and relief flow characteristics.

2 Normative references

The following documents are referred to in the text in such a way that some or all of their content constitutes requirements of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

ISO 5598, *Fluid power systems and components — Vocabulary*

ISO 6358-1, *Pneumatic fluid power — Determination of flow-rate characteristics of components using compressible fluids — Part 1: General rules and test methods for steady-state flow*

ISO 6953-1, *Pneumatic fluid power — Compressed air pressure regulators and filter-regulators — Part 1: Main characteristics to be included in literature from suppliers and product-marking requirements*

ISO 10094-1:2021, *Pneumatic fluid power — Electro-pneumatic pressure control valves — Part 1: Main characteristics to include in the supplier's literature*

3 Terms and definitions

For the purposes of this document, the terms and definitions given in ISO 5598, ISO 6953-1 and ISO 10094-1 and the following apply.

ISO and IEC maintain terminological databases for use in standardization at the following addresses:

- ISO Online browsing platform: available at <https://www.iso.org/obp>
- IEC Electropedia: available at <https://www.electropedia.org/>

3.1

response time

time from initial electrical signal change to an observed output pressure equal to 90 % of the total change in pressure

3.2

settling time

time lapse from initial change to the time from which the observed output pressure remains between 95 % and 105 % of its total change in pressure

3.3

shifting time

time from initial electrical signal change to an observed output pressure equal to 10 % of the total change in pressure

4 Symbols and units

Table 1 — Symbols and units

Description	Symbol	Units
Maximum sonic conductance at the inlet	$C_{f,max}$	$m^3/(s \cdot Pa)$ (ANR) ^b
Sonic conductance at the exhaust	C_r	$m^3/(s \cdot Pa)$ (ANR) ^b
Hysteresis	H	% FS
Linearity	L	% FS
Sensitivity	m	Pa/V, Pa/mA or Pa/numerical signal
Offset	O	%
Atmospheric pressure	p_{atm}	Pa
Reference pressure	p_0	Pa
Total relative pressure at the inlet port ^a	p_1	Pa
Total relative pressure at the outlet port ^a	p_2	Pa
Maximum inlet pressure	$p_{1,max}$	Pa
Maximum regulated pressure	$p_{2,max}$	Pa
Volume flow rate at standard reference atmosphere	q_V	m^3/s (ANR) ^b
Maximum volume flow rate at the inlet	$q_{V,f,max}$	m^3/s (ANR) ^b
Volume flow rate at the outlet	$q_{V,r}$	m^3/s (ANR) ^b
Repeatability	r	% FS
Resolution	S	% FS
Reference temperature	T_0	K

^a As described in ISO 11727.

^b The reference atmosphere is defined in ISO 8778, i.e.: $T_0 = 293,15$ K, $p_0 = 100$ kPa (1 bar) and a relative humidity of 65 %.

Table 1 (continued)

Description	Symbol	Units
Temperature at the inlet port ^a	T_1	K
Temperature at the outlet port ^a	T_2	K
Electrical control signal	w	V, mA or numerical signal
Pressure difference	Δp	Pa
Maximal difference of hysteresis	$\Delta p_{2,h,max}$	Pa
Maximal difference of the linearity	$\Delta p_{2,l,max}$	Pa
^a As described in ISO 11727. ^b The reference atmosphere is defined in ISO 8778, i.e.: $T_0 = 293,15$ K, $p_0 = 100$ kPa (1 bar) and a relative humidity of 65 %.		

5 Test conditions

5.1 Gas supply

Unless otherwise specified, testing shall be conducted with compressed air. If another gas is used, it shall be noted in the test report.

5.2 Temperature

The ambient, fluid and the component-under-test temperatures shall be maintained at $23\text{ °C} \pm 10\text{ °C}$ during all the tests.

5.3 Pressures

5.3.1 General

The specified pressures shall be maintained within $\pm 2\%$.

5.3.2 Inlet pressure

The inlet pressure used for testing shall be the lower of the following pressures:

- the maximum regulated pressure, $p_{2,max}$, plus 200 kPa (2 bar); and
- the specified maximum inlet pressure, $p_{1,max}$.

5.3.3 Test pressures

The preferential test pressures are chosen as approximately equal to 20 %, 40 %, 60 %, 80 % and 100 % of the maximum of the setting pressure scale.

5.3.4 Checking

It shall be periodically verified that no pressure bleed of measuring instruments is obstructed by solid or liquid particles.

5.4 Electrical supplies

The tests shall be carried out under nominal electrical conditions.

6 Test procedures

6.1 Test conditions

The component under test shall be used according to the manufacturer's application instructions.

6.2 Inlet pressure

During every measurement concerning the static or dynamic tests described in [Clauses 7](#) to [11](#), the inlet pressure, p_1 , shall be constant (within 10 % FS).

In the case of the dynamic tests as described in [Clause 11](#), a tank buffer shall be used in order to reduce the inlet pressure, p_1 , fluctuations, as indicated in [Figure 10](#).

6.3 Static tests

During every measurement series concerning static tests described in [Clauses 7](#), [8](#), [9](#) and [10](#), as soon as the steady conditions are reached, every series of results obtained with related specified test conditions shall be recorded. When these measurements are performed step by step, slowly modify the conditions to prevent instability.

NOTE 1 [Figures 1](#), [7](#), [9](#) and [10](#) represent typical circuits that do not show the electrical supply circuit necessary to operate electrically modulated pneumatic valves and that do not contain all the necessary safety devices for protection against hazards that can be caused by the failure of a component or piping. It is important that those responsible for conducting the tests take into account the necessity to protect personnel and property.

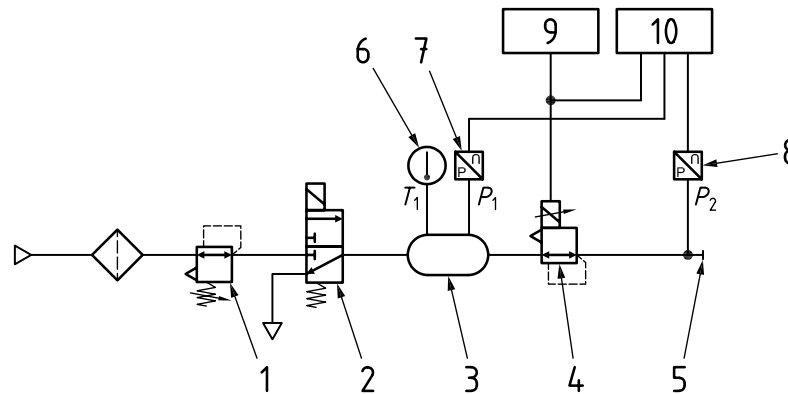
NOTE 2 The symbols used in the circuit diagrams shown in [Figures 1](#), [7](#), [9](#) and [10](#) are in accordance with ISO 1219-1.

7 Control signal/pressure static-characteristics test at null forward or relief flow rate

7.1 Test installation

7.1.1 Test circuit

[Figure 1](#) represents a typical test circuit for the control signal/pressure static characteristics testing. This test is conducted with no forward flow and with the relief port open to atmosphere. For all tests described in [7.2](#), apply the inlet pressure chosen according to [5.3.2](#).

**Key**

- | | | | |
|---|--|----|---|
| 1 | supply pressure regulator | 6 | inlet temperature T_1 measuring element |
| 2 | shut off valve | 7 | inlet pressure p_1 transducer |
| 3 | inlet volume or optional pressure measuring tube with transition connector | 8 | regulated pressure p_2 transducer |
| 4 | component under test | 9 | signal generator |
| 5 | plug | 10 | data recorder |

Figure 1 — Typical test circuit for control signal/pressure characterization

7.1.2 Pressure measurement

The inlet pressure sensor is connected to the volume or pressure-measuring tube with transition connector in accordance with ISO 6358-1. The regulated pressure sensor is an external measurement sensor, even if the component under test has an internal pressure sensor. The regulated pressure transducer shall be connected as close as possible to the outlet port.

7.2 Test procedures

7.2.1 Control signal/pressure static characteristic test

Using a signal generator to create a triangular signal to explore the control signal full-scale (0 % to 100 %), record the electrical control signal, w , in the X-axis and the regulated pressure, p_2 , in the Y-axis of a recorder so as to obtain a hysteresis curve.

The triangular electrical control signal shall evolve with a sufficiently low ramp speed so as to avoid dynamic effects and influence the regulated pressure measurements: 0,5 % of full-scale per second is the recommended ramp speed.

7.2.2 Minimum regulated pressure test

Leave the component under test pressurized with the minimum control signal (0 %) at rest for at least 5 min.

From the minimum electrical control signal (0 %), measure the regulated pressure, p_2 for the following control signal values. This defines response to the lower portion of the signal:

- 0 %, 0,5 %, 1 % of the control signal full-scale;
- then every 1 % up to 5 % of the control signal full-scale.

Every measurement is made after a rest time of 10 s at each stage. The measurements shall always be made by increasing the control signal.

7.2.3 Resolution test

7.2.3.1 From the minimal electrical control signal (0 %), gradually modify the electrical control signal value by increasing values only, until reaching the value corresponding to 15 % of the regulated pressure full-scale.

7.2.3.2 Note this electrical control signal value, w_{stop} , and record the pressure evolution as a function of the electrical signal.

7.2.3.3 Maintain this state for more than 10 s and gradually re-increase the input signal. Then note the electrical control signal, w_{start} , for which the regulated pressure, p_2 , starts re-increasing.

7.2.3.4 Repeat the operations described in [7.2.3.2](#) and [7.2.3.3](#) for the electrical control signal values corresponding to 50 % and 85 % of the regulated pressure full-scale. Gradually modify the control signal, by increasing values only, until reaching these values.

7.2.4 Repeatability test

Using a signal generator to create a stepped signal between 0 % to 15 %, 15 % to 50 % and 50 % to 85 % of the electrical control signal full-scale, according to [Figure 2](#), record the regulated pressure, p_2 , as a function of time for at least 20 periods.

The frequency of the electrical control signal shall be sufficiently low so as to have a good stabilization of the regulated pressure at 15 %, 50 % and 85 % of the electrical control signal full-scale.

At each period indicated by the index $j = 1, \dots, 20$, when the regulated pressure is stabilized for 15 %, 50 % and 85 % of the electrical control signal full scale (hereinafter referred to as x), note the corresponding regulated pressure, $p_{2,x,j}$.

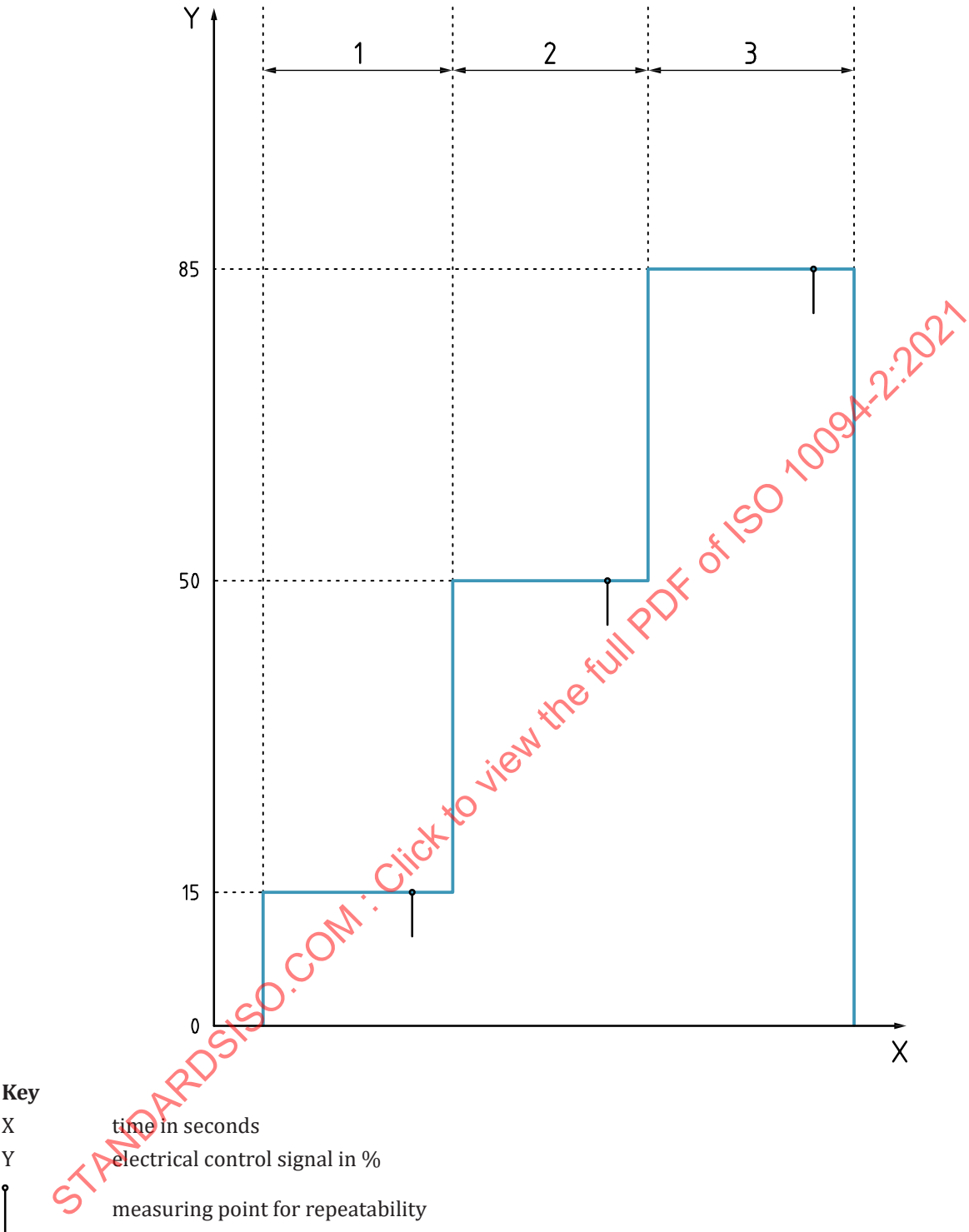


Figure 2 — Repeatability test

7.3 Calculation of characteristics

7.3.1 Characteristic curve

For each value of the control signal, calculate the mean value of the two corresponding pressures measured according to the procedure described in 7.2.1, respectively with an increasing and a decreasing control signal.

Plot the mean pressure curve as a function of the control signal as represented in [Figure 3](#).

The characteristic line is the straight line passing by the mean regulated pressure values of 5 % and 95 % of the regulated pressure full-scale according to [Figure 3](#).

The offset of the straight line shall be determined by the intersection of the straight line with the abscissa axis (regulated pressure, p_2 , equal to 0 kPa) as shown in [Figure 3](#) and [Figure 6](#).

The sensitivity and the offset of the straight line shall be indicated on the graph, as represented in [Figure 3](#).

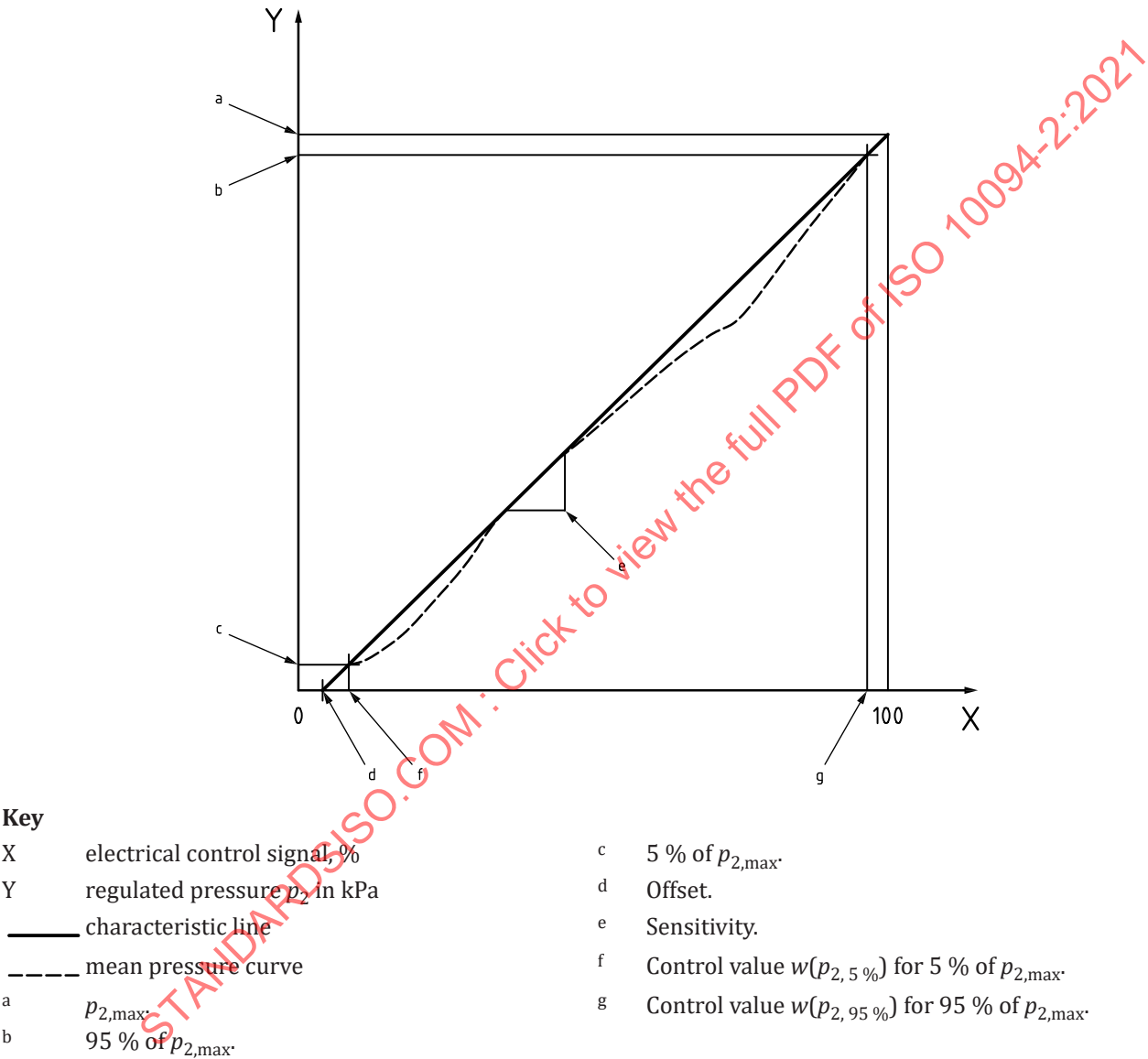


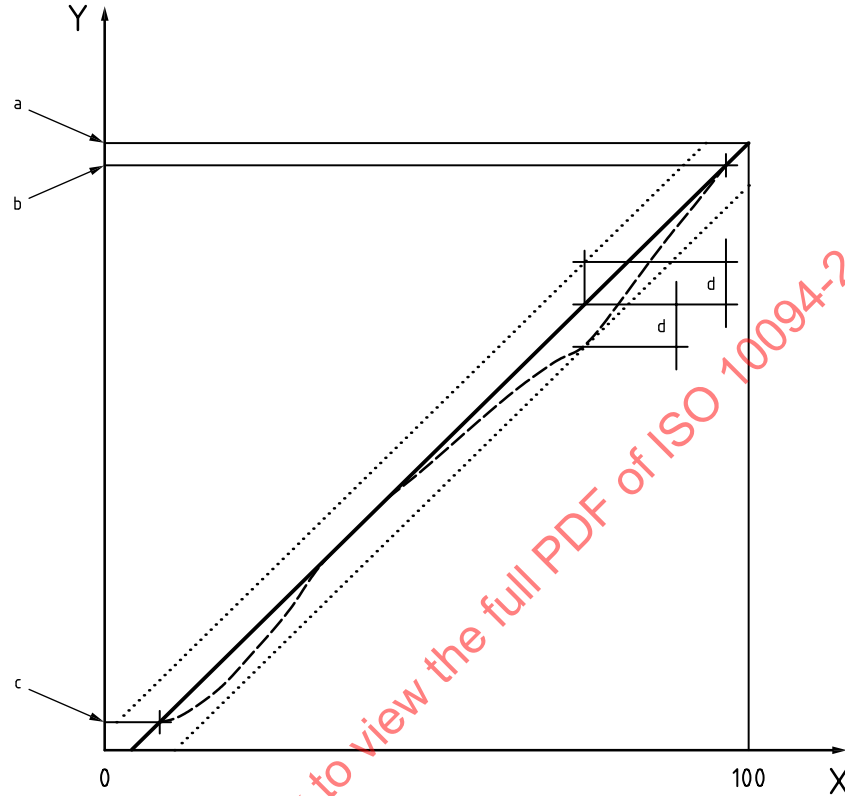
Figure 3 — Determination of the characteristic curve

7.3.2 Linearity

For each control signal value corresponding to regulated pressure value between 5 % and 95 % of the regulated pressure full-scale, calculate, in absolute value, the difference between the mean regulated pressure value calculated in [7.3.1](#) and the corresponding value on the characteristic straight line plotted in [7.3.1](#).

Determine the maximal difference, $\Delta p_{2,l,max}$, according to Figure 4, and calculate the linearity value, L , expressed as a percentage of the regulated pressure full-scale using Formula (1):

$$L = \frac{|\Delta p_{2,l,max}|}{p_{2,max}} \cdot 100 \quad (1)$$



Key

X electrical control signal, %

Y regulated pressure p_2 , in kPa

— characteristic line

- - - mean pressure curve

..... maximum linearity limits

a $p_{2,max}$

b 95 % of $p_{2,max}$

c 5 % of $p_{2,max}$

d $\Delta p_{2,l,max}$

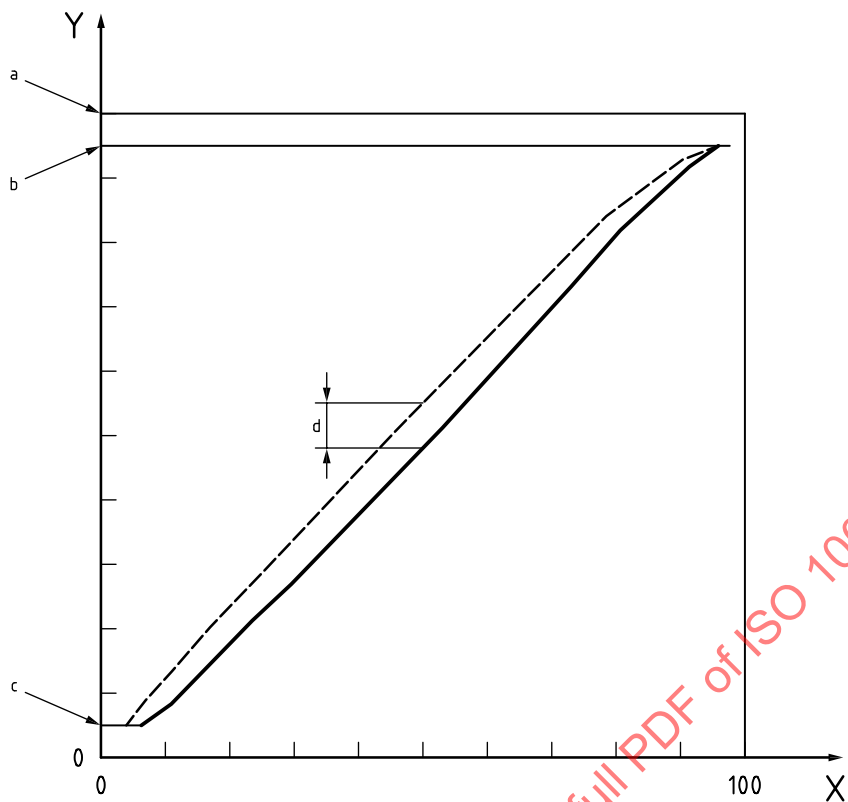
Figure 4 — Representation of the maximal scattering of linearity

7.3.3 Control signal/pressure hysteresis

For each control signal value corresponding to regulated pressure value between 5 % and 95 % of the regulated pressure full-scale, calculate in absolute value, the difference between the regulated pressure values p_2 measured respectively with an increasing and a decreasing control signal. These values are obtained according to the procedure described in 7.2.1.

Determine the maximal difference, $\Delta p_{2,h,max}$, according to Figure 5. Calculate the hysteresis characteristic value, H , evaluating this difference in percentage of the regulated pressure full-scale according to Formula (2):

$$H = \frac{|\Delta p_{2,h,max}|}{p_{2,max}} \cdot 100 \quad (2)$$



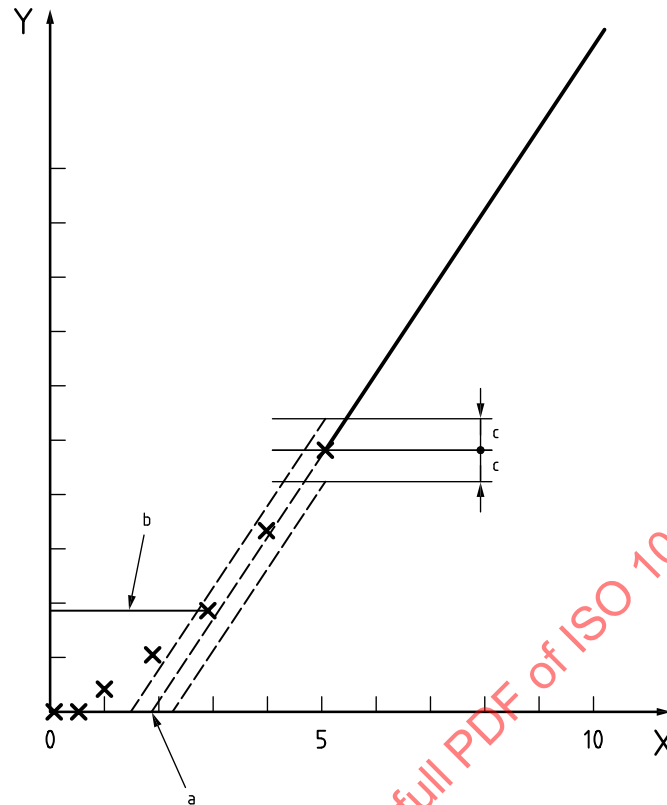
Key	
X electrical control signal, %	—— characteristic line measured with increasing signal
Y regulated pressure p_2 , in kPa	----- characteristic line measured with decreasing signal
	a $p_{2,max}$
	b 95 % of $p_{2,max}$
	c 5 % of $p_{2,max}$
	d $\Delta p_{2,h,max}$

Figure 5 — Representation of the maximal scattering of hysteresis difference

7.3.4 Minimum regulated pressure

With the data measured according to the procedure described in 7.2.2, determine the pressure at the first point from which all subsequent data points fall within the allowable limits of linearity of the control signal/pressure characteristic curve, as shown in Figure 6.

This regulated pressure value, expressed as a percentage of the regulated pressure full-scale, corresponds to the minimum regulated pressure value.

**Key**

X electrical control signal, %
 Y regulated pressure p_2 , in kPa
 — characteristic line

a Offset.
 b Minimum regulated pressure.
 c $\Delta p_{2,l,max}$.

Figure 6 — Graphic determination of the minimum regulated pressure value and of the offset

7.3.5 Resolution

7.3.5.1 For each of the three tests performed according to 7.2.3, for electrical control signal values corresponding to 15 %, 50 % and 85 % of the regulated pressure full-scale, calculate the corresponding resolution, expressed as a percentage of the control signal full-scale, using Formula (3):

$$S = \frac{w_{\text{start}} - w_{\text{stop}}}{w_{\text{max}} - w_{\text{min}}} \cdot 100 \quad (3)$$

7.3.5.2 Calculate the resolution by taking the maximal value of the three values obtained in 7.3.5.1.

7.3.6 Repeatability

Using the stabilized regulated pressures values, $p_{2,x,j}$, obtained according to the procedure described in 7.2.4, calculate the repeatability value, r_x , expressed as a percentage of the regulated pressure full-scale, using Formula (4):

$$r_x = \frac{p_{2,x,\text{max}} - p_{2,x,\text{min}}}{p_{2,\text{max}}} \cdot 100 \quad (4)$$

where

$p_{2,x,\max}$ is the maximum value of the 20 repeat measurements $p_{2,x,j}$ ($j=1\dots 20$) from the measurement series for the percentage x ($x = 15\%$, 50% or 85%) of the regulated full-scale pressure; and

$p_{2,x,\min}$ is the minimum value of the 20 repeat measurements $p_{2,x,j}$ ($j=1\dots 20$) from the measurement series for the percentage x ($x = 15\%$, 50% or 85%) of the regulated full-scale pressure.

The value r for the repeatability shall be the highest value from the calculated values $r_{15\%}$, $r_{50\%}$ and $r_{85\%}$.

7.3.7 Sensitivity

With the mean regulated pressure values of 5% ($p_{2,5\%}$) and 95% ($p_{2,95\%}$) of regulated pressure full scale, measured respectively with electrical control signal $w(p_{2,5\%})$ and $w(p_{2,95\%})$ and used to plot the characteristic line in paragraph 7.3.1, the sensitivity, expressed as Pa/V, Pa/mA or Pa/numerical signal, is calculated using Formula (5):

$$m = \frac{p_{2,95\%} - p_{2,5\%}}{w(p_{2,95\%}) - w(p_{2,5\%})} \cdot 100 \quad (5)$$

7.3.8 Offset

The offset, expressed in percentage, shall be calculated using Formula (6):

$$O = \frac{m \cdot w(p_{2,5\%}) - p_{2,5\%}}{m \cdot (w_{\max} - w_{\min})} \cdot 100 \quad (6)$$

8 Flow/pressure static characteristics test

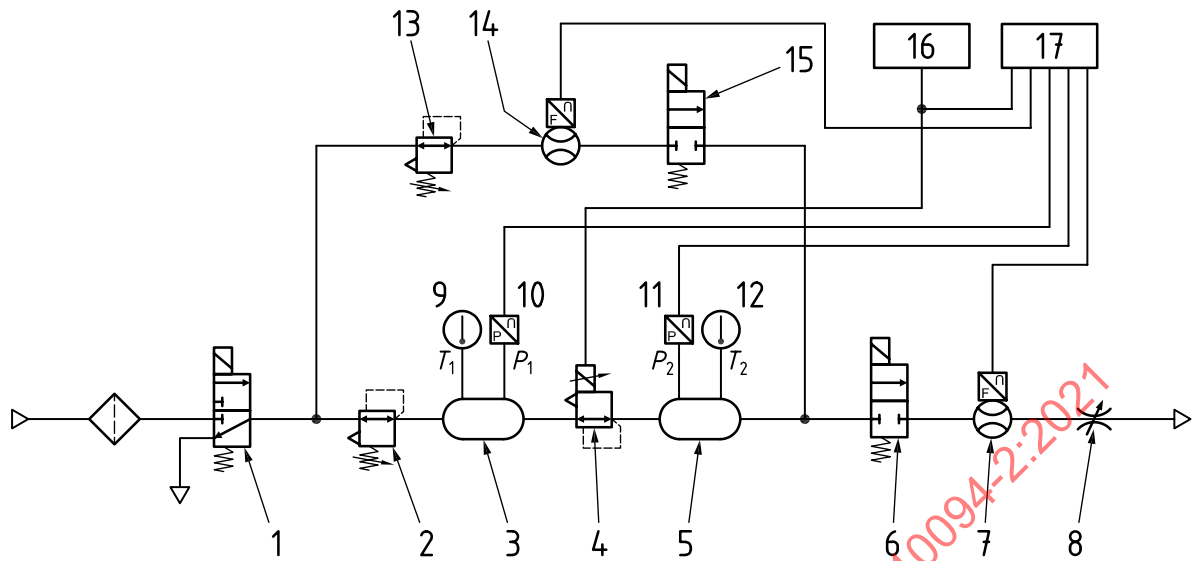
8.1 Test circuit for flow rate measurement

A suitable test circuit, as shown in Figure 7, shall be used for measuring forward or relief flow rates. This test circuit combines:

- the in-line test circuit, as described in ISO 6358-1 for characterizing, in steady state conditions, the components with upstream and downstream pressure-measuring tubes and transition connectors (used for forward flow rate measurements), and
- the exhaust-to-atmosphere test circuit, as described in ISO 6358-1 for characterizing, in steady state conditions, the components exhausting directly to atmosphere (used for relief flow rate measurements).

This test circuit shall be used for:

- the flow-pressure static characteristics measurements, and
- the pressure regulation characteristics measurements.



Key

- | | |
|---|---|
| 1 shut-off valve | 10 inlet pressure p_1 transducer |
| 2 supply pressure regulator | 11 regulated pressure p_2 transducer |
| 3 pressure measuring tube with transition connector | 12 temperature T_2 measuring element |
| 4 component under test | 13 pressure regulator (for relief flow rates) |
| 5 pressure measuring tube with transition connector | 14 relief flow meter |
| 6 solenoid valve | 15 solenoid valve |
| 7 forward flow meter | 16 signal generator |
| 8 flow control valve (for forward flow rates) | 17 data acquisition system (optional) |
| 9 inlet temperature T_1 measuring element | |

NOTE If the component under test already operates with an external sensor, place it at the same place as the regulated pressure sensor.

Figure 7 — Test circuit for flow rate/pressure characterization and pressure regulation

8.2 General requirements

8.2.1 The component under test shall be located in the test circuit so as to connect its inlet port to the upstream transition connector and pressure-measuring tube, and its exhaust port to the atmosphere. Its outlet port is connected to a transition connector and a pressure-measuring tube enabling measurement of the regulated pressure, p_2 .

8.2.2 Pressure-measuring tubes and transition connectors shall be in accordance with ISO 6358-1.

8.2.3 Components 1, 2, 3, 9 and 10 in [Figure 7](#) correspond to the upstream part of the test circuit used for forward flow rates measurements. These components shall be also used for relief flow rate measurements as the inlet port of the component under test shall be connected to the supply circuit, following the normal use of the component.

8.2.4 Components 5, 6, 7, 8, 11, and 12 in [Figure 7](#) correspond to the downstream part of the test circuit used for forward flow rates measurements.

8.2.5 The sonic conductances of the supply pressure regulator 2 and of the solenoid valve 6 should be at least twice the forward sonic conductance of the component under test.

8.2.6 Components 5, 11, 12, 13, 14, and 15 in [Figure 7](#) correspond to the upstream part of the test circuit used for relief flow rate measurements.

8.2.7 The sonic conductances of the pressure regulator 13 and of the solenoid valve, 15, should be at least twice the relief sonic conductance of the component under test.

8.2.8 The flow-meters shall always be located at the outlet port in order to measure the actual forward or relief flow rate.

8.3 Test procedures

8.3.1 Initial test procedure

8.3.1.1 Install the electro-pneumatic continuous pressure control valve according to [Figure 7](#), without flow, with shut-off valve, solenoid valves and flow control valve closed.

8.3.1.2 Open shut-off valve, 1, and set the pressure regulator, 2, to apply the inlet pressure, p_1 , chosen according to [5.3.2](#).

8.3.1.3 From the minimal electrical control signal (0 %), gradually modify the control signal by increasing values only, until reaching the regulated pressure value, p_2 , corresponding to 20 % of the regulated pressure full-scale.

8.3.1.4 Follow successively the procedure described in [8.3.2](#) for forward flow rates and then the procedure described in [8.3.3](#) for relief flow rates.

8.3.2 Forward flow rate/pressure characteristics test

8.3.2.1 Open the solenoid valve 6. By using the flow rate control valve 8, let the air pass through the component under test.

8.3.2.2 When the flow is steady, measure the forward flow rate using the flow meter, 7, the corresponding regulated pressure, p_2 , using the pressure transducer, and the inlet temperature, T_1 .

8.3.2.3 Continue the measurements by gradually modifying the flow value, by increasing values only until reaching the maximal flow rate in the test circuit. Measure the additional data for a decreasing forward flow rate until zero. During the variations of the forward flow (increasing and decreasing), keep the inlet pressure, p_1 , constant.

8.3.3 Relief flow rate/pressure characteristics test

8.3.3.1 Set the pressure regulator, 13, at the same pressure value as the regulated pressure value of the component under test obtained without flow at the end of the procedure described in [8.3.2.3](#). Close the solenoid valve, 6, and open the solenoid valve, 15, to apply this pressure on the outlet side of the component under test.

8.3.3.2 Increase the regulated pressure using the pressure regulator, 13. When the flow is steady, measure the relief flow using the flow meter 14, the corresponding regulated pressure, p_2 , using the pressure transducer and the temperature, T_2 , since the air passes through the exhaust port of the component under test.

8.3.3.3 Continue the measurements by gradually increasing the flow rate by increasing the pressure using the pressure regulator until the pressure reaches a level of the maximum regulated pressure

plus 200 kPa (2 bar). Measure the additional data for decreasing pressure until the flow rate reaches zero. During the variations of the relief flow (increasing and decreasing), keep the inlet pressure, p_1 , constant. Close the solenoid valve, 15.

8.3.4 Procedure for other control signal values

Repeat the above procedures described in 8.3.1.4 for control signal values corresponding to about 40 %, 60 %, 80 % and 100 % of the regulated pressure full-scale. Without flow, gradually modify the control signal, by increasing values only, until reaching these values.

8.4 Calculation of characteristics

8.4.1 Characteristic curves

8.4.1.1 From the measurements obtained for the electrical control signal corresponding approximately to about 20 % of the regulated pressure full scale, for each forward flow rate value, calculate the mean value of the two corresponding regulated pressures, p_2 , measured according to the procedure described in 8.3.2, respectively with increasing and decreasing forward flow rates.

Plot in a graph the mean regulated pressure values, as a function of the forward flow rate, as represented in the first quadrant of Figure 8.

8.4.1.2 From the measurements obtained for the electrical control signal corresponding approximately to about 20 % of the regulated pressure full scale, for each relief flow rate value, calculate the mean value of the two corresponding regulated pressures, p_2 , measured according to the procedure described in 8.3.3, respectively with increasing and decreasing relief flow rates.

Plot in a graph the mean regulated pressure values, as a function of the relief flow rate, as represented in the second quadrant of Figure 8.

8.4.1.3 Repeat the calculation procedure and layout for the four other control signal values corresponding to 40 %, 60 %, 80 % and 100 % of the regulated pressure full-scale.

8.4.2 Flow rate/pressure hysteresis

For each forward flow rate or relief flow rate value, calculate the difference between the regulated pressure values measured, respectively with increasing and decreasing flow rates. These values are measured according to the procedures described in 8.3.2 and 8.3.3.

Determine the maximal difference, $\Delta p_{2,h,max}$, and, using Formula (2), calculate the hysteresis characteristic value, expressed as a percentage of the regulated pressure full-scale.

8.4.3 Maximum forward sonic conductance

8.4.3.1 Graphically determine the maximum forward flow rate, $q_{V,f,max}$, as the intersection of an extension line of forward flow rate-pressure characteristic curves obtained in 8.4.1.1 with the abscissa axis (regulated pressure is null in relative value), according to Figure 8.

8.4.3.2 Calculate the value of the maximal forward sonic conductance, $C_{f,max}$, by dividing this flow rate value by the inlet pressure in accordance with ISO 6358-1, using Formula (7):

$$C_{f,max} = \frac{q_{V,f,max}}{p_1 + p_{atm}} \sqrt{\frac{T_1}{T_0}} \quad (7)$$

NOTE The square root is necessary to take into account the test upstream temperature T_1 deviation from the reference temperature, T_0 , as described in ISO 8778.

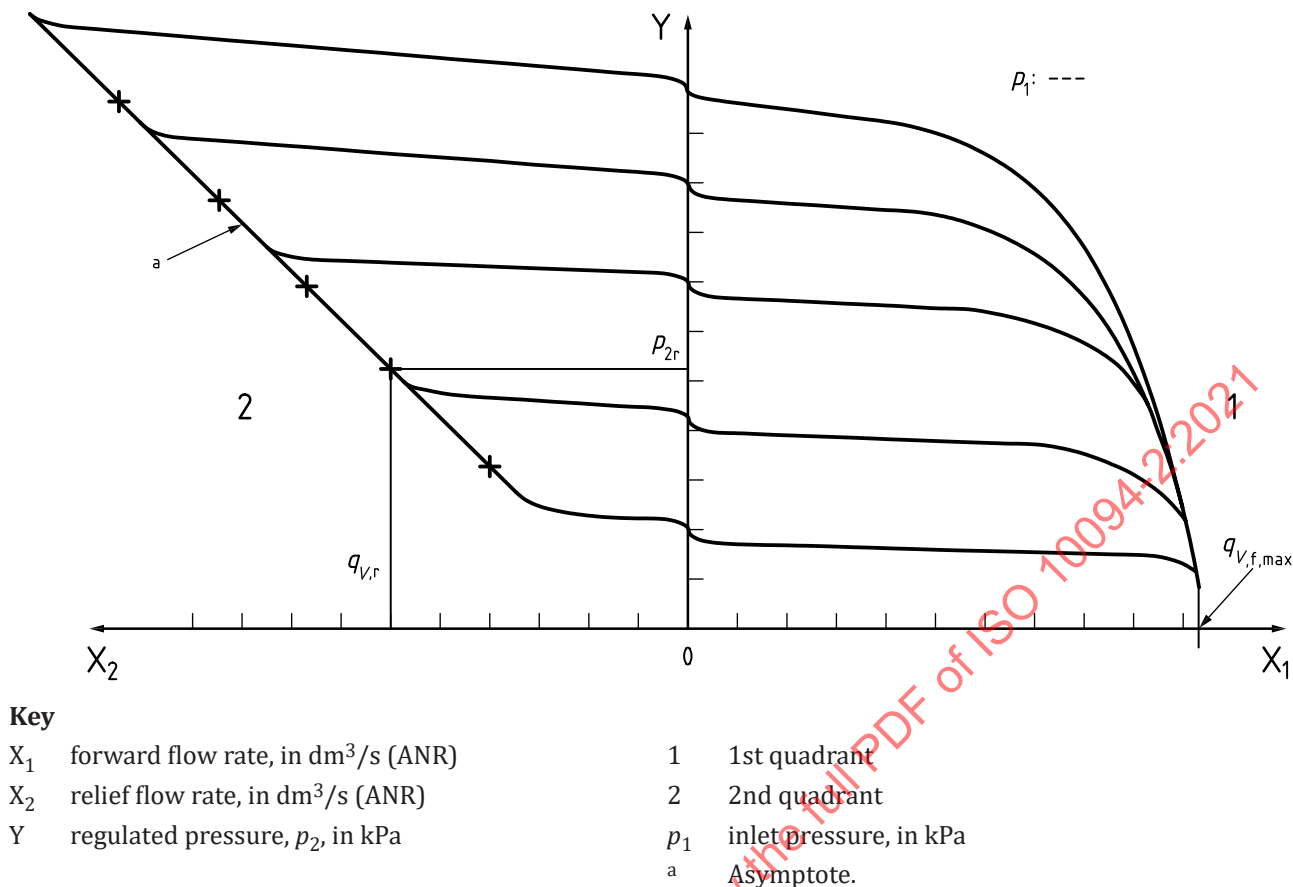


Figure 8 — Graphic determination of the necessary values for calculation of the sonic conductances

8.4.4 Maximum relief sonic conductance

8.4.4.1 Choose graphically 5 points all over the asymptote of the relief flow rate/pressure curves obtained in 8.4.1.2 according to Figure 8. Each one of them is defined by a relief flow rate value, $q_{V,r}$ and a regulated pressure value, p_{2r} .

8.4.4.2 For each one of these points, calculate the corresponding sonic conductance value, C_r , by dividing the flow rate value by the regulated pressure in accordance with ISO 6358-1 (upstream pressure in this case), using Formula (8):

$$C_r = \frac{q_{V,r}}{p_2 + p_{\text{atm}}} \sqrt{\frac{T_2}{T_0}} \quad (8)$$

NOTE The squared root is necessary to take into account the test upstream temperature, T_2 , deviation from the reference temperature, T_0 , as described in ISO 8778.

8.4.4.3 Calculate the maximal relief sonic conductance by determining the average value of these five values.

9 Pressure regulation characteristics test

9.1 Test circuit

The same test circuit as shown in [Figure 7](#) shall be used for the pressure regulation test. Only the part of the circuit for measuring forward flow rate shall be used.

The general requirements [8.2.1](#) to [8.2.5](#) and [8.2.8](#) concerning the measurement of forward flow rates shall be respected.

9.2 Test procedure

9.2.1 Install the electro-pneumatic continuous pressure control valve according to [Figure 7](#), without flow, with shut-off valve, solenoid valves and flow control valve closed.

9.2.2 Open shut-off valve, 1, and set the pressure regulator, 2, to apply an inlet pressure, p_1 , such as it will be very much higher than the setting range of the component under test and shall be reasonably tested, without exceeding the inlet capacity of the component under test.

9.2.3 From the minimal electrical control signal (0 %) gradually modify the control signal by increasing values only, until reaching the value corresponding to 20 % of the regulated pressure full-scale.

9.2.4 Open the solenoid valve, 6. By using the flow rate control valve, set the forward flow rate to 10 % of the maximal flow rate, $q_{V,f,max}$, determined in [8.4.3.1](#). Set the inlet pressure, p_1 , once again to reach the initial value determined in [9.2.2](#).

9.2.5 Reduce the inlet pressure, p_1 , and measure the corresponding regulated pressure, p_2 , using the pressure transducer, 11, while maintaining the flow rate constant, up to the lowest inlet pressure allowing the chosen flow rate to be maintained.

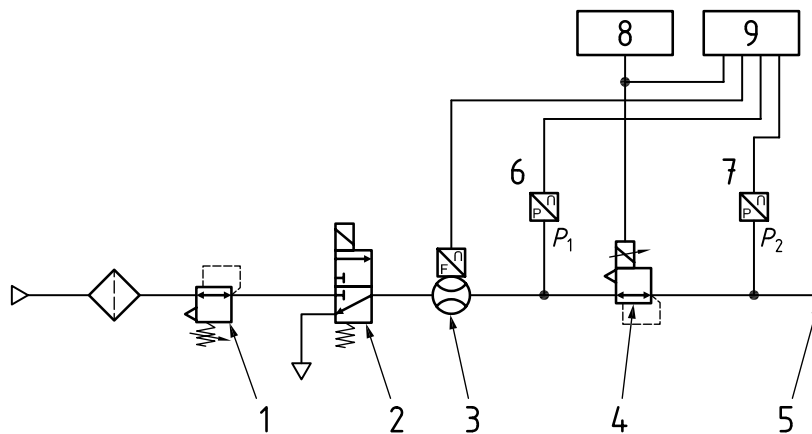
9.2.6 Repeat the procedures [9.2.1](#) to [9.2.5](#) for control signal values corresponding to about 40 %, 60 %, 80 % and 100 % of the regulated pressure full-scale. Without flow, increase gradually the control signal until reaching these values.

10 Leakage at null forward flow rate or relief flow rate characteristic test

10.1 Test circuit

[Figure 9](#) represents a typical test circuit for characterizing the leakage at null forward flow rate or relief flow rate. This figure uses the upstream part of the test circuit for the in-line test, as described in ISO 6358-1, for characterizing in steady state conditions the components with upstream and downstream pressure-measuring tubes, adding the following indications:

- the connector at the outlet port is plugged to guarantee a null forward flow rate or relief flow rate. The regulated pressure transducer shall be connected as close as possible to the outlet port;
- the flow meter is placed upstream in the supply line.



Key

- | | | | |
|---|---------------------------|---|-------------------------------------|
| 1 | supply pressure regulator | 6 | inlet pressure p_1 transducer |
| 2 | shut-off valve | 7 | regulated pressure p_2 transducer |
| 3 | leakage flow meter | 8 | signal generator |
| 4 | component under test | 9 | data acquisition system (optional) |
| 5 | plug | | |

Figure 9 — Typical test circuit for leakage characterization

10.2 Test procedure

Apply the inlet pressure, p_1 , chosen according to [5.3.2](#).

Measure the leakage flow at the inlet pressure as described in [5.3.2](#) and steady-state conditions with set pressures of 0 %, 15 %, 50 %, 85 % and 100 % of FS.

The measurements shall be made only by increasing the control signal.

10.3 Calculation of characteristic

For each value of the control signal described in [10.2](#), determine the leakage value. The characteristic leakage value is indicated as the maximum value of the inlet leakage flow rate of these control signal values.

11 Dynamic characteristics – Step responses

11.1 Test Installation

[Figure 10](#) represents a typical test circuit for the dynamic characterization of electro-pneumatic continuous pressure control valves.

11.1.2 The port of every test tank at which the component under test is connected shall have a diameter at least equal to the one of the outlet port of the component under test.

11.1.3 Maintain as short as possible the length of the piping between the outlet port of the component under test and the tank.

11.1.4 The buffer tank, 2, used to limit inlet pressure fluctuations shall be as close as possible to the inlet port of the component under test.

11.1.5 The pressure sensor, 9, is an external sensor installed on one of the ports of the test tank situated perpendicularly to the inlet port of the tank as shown in [Figure 10](#).

NOTE If the component under test already operates with an external sensor, place it at the same place as the measurement sensor.

11.1.6 Use an oscilloscope or other appropriate electronic equipment to record the time dependent electrical control and pressure signals.

NOTE For procedures that can be used for determining a frequency response, see [Annex A](#).

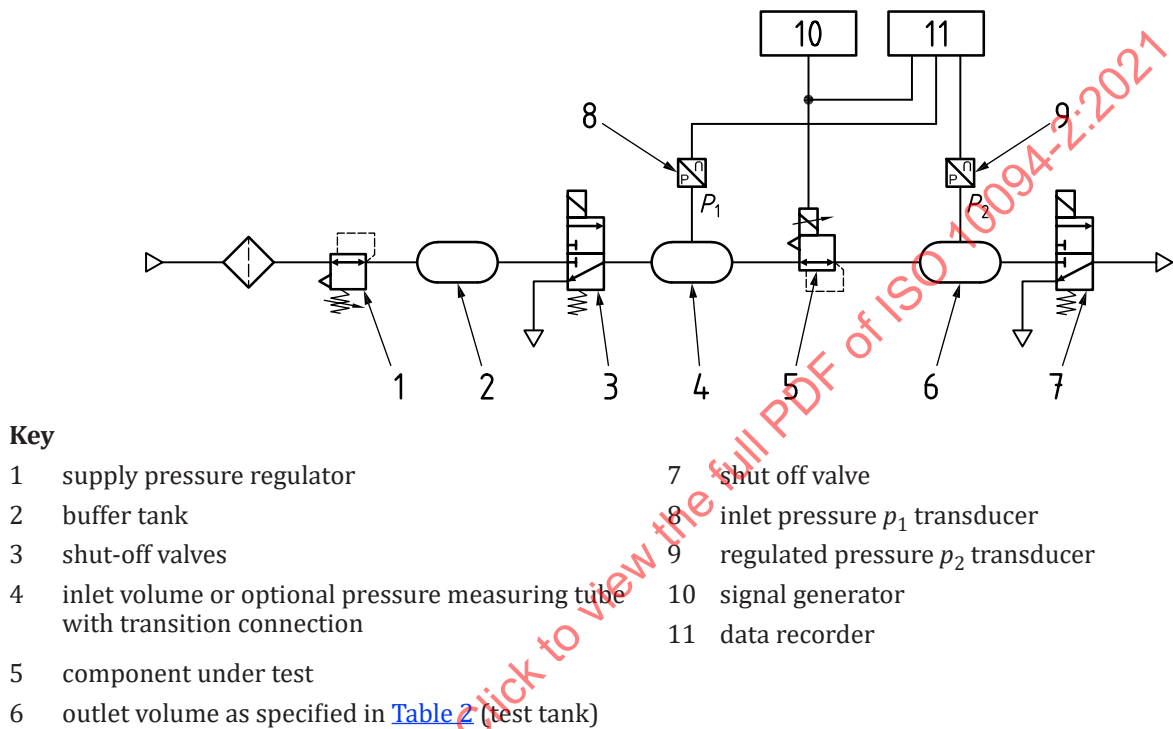


Figure 10 — Test circuit for dynamic characterization with a tank

11.2 Test procedures

11.2.1 According to the port size of the pressure control valve under test, choose a tank whose volume corresponds to one of those in [Table 2](#).

11.2.2 Install the electro-pneumatic continuous pressure control valve according to [Figure 10](#), without flow. Apply the inlet pressure, p_1 , chosen according to [5.3.2](#).

11.2.3 From the minimal electrical control signal (0 %) generate a control signal step with amplitude of 100 % of its full scale. Simultaneously record the evolution of the control signal and the evolution of the measured pressure at tank level throughout the tank charge until the pressure becomes steady in the tank.

11.2.4 From the maximal electrical control signal (100 %) generate a control signal step up to 0 % of its full scale. Simultaneously record the evolution of the control signal and the evolution of the measured pressure at tank level throughout the tank discharge until the pressure becomes steady in the tank.

11.2.5 Repeat test procedures [11.2.3](#) and [11.2.4](#) for the following control signal steps:

— 25 % to 75 %;

— 45 % to 55 %.

11.2.6 Repeat test procedures 11.2.2 to 11.2.5 for the three other test tank volume values of Table 2.

Table 2 — Volume values of the test tanks depending on the control valve port size

Port size	Test tank volume (dm ³)			
	V_0	V_1	V_2	V_3
M3	Pressure sensor directly connected	0,02	0,05	0,1
M5	Pressure sensor directly connected	0,05	0,1	0,2
M7	Pressure sensor directly connected	0,1	0,2	0,5
G1/8	Pressure sensor directly connected	0,1	0,5	1
G1/4 G3/8	Pressure sensor directly connected	0,5	1	2
G1/2 G3/4	Pressure sensor directly connected	1	2	10
≥ G1	Pressure sensor directly connected	2	10	20

11.3 Calculation of characteristics

11.3.1 Charge characteristic curves

For each of the three control steps, with the same time scale for the four volume values, plot in the same graph the time responses of the pressure evolution in the tank during the charge of the four volumes, as shown in ISO 10094-1:2021, Figure 5.

Use, as a reference for the time scale, the time of the initiation of the control signal steps.

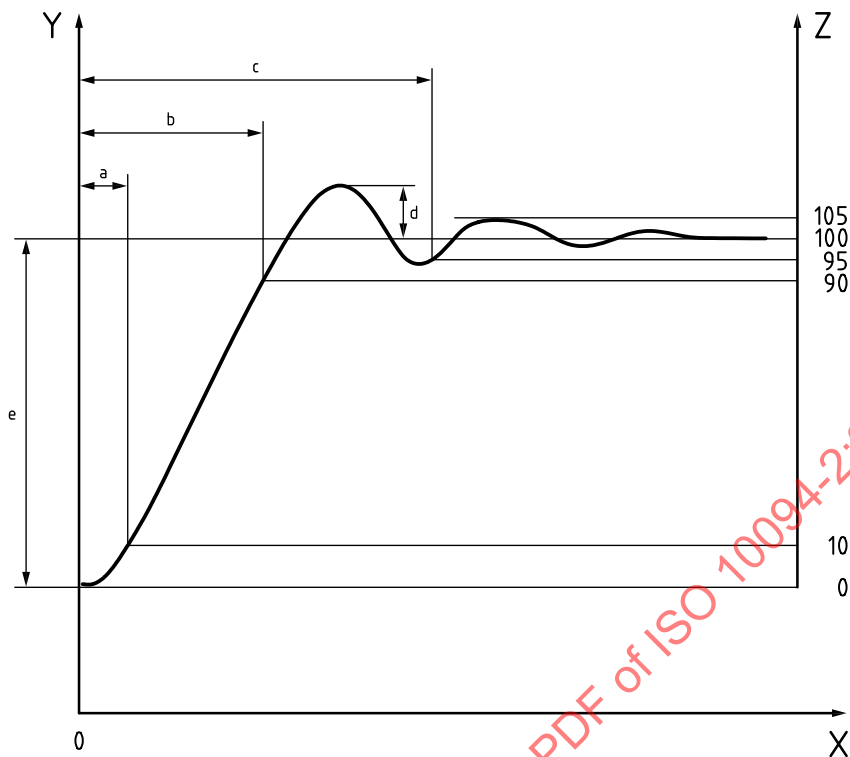
11.3.2 Discharge characteristic curves

For each of the three control steps, with the same time scale for the four volume values, plot in the same graph the time responses of the pressure evolution in the tank during the discharge of the four volumes as shown in ISO 10094-1:2021, Figure 6.

Use, as a reference for the time scale, the time of the initiation of the control signal steps.

11.3.3 Charge characteristics

From the charge characteristics curves obtained in 11.3.1, determine for each control step and for each of the four volumes, the shifting time, the response time, the settling time and the overshoot, as defined in Figure 11.



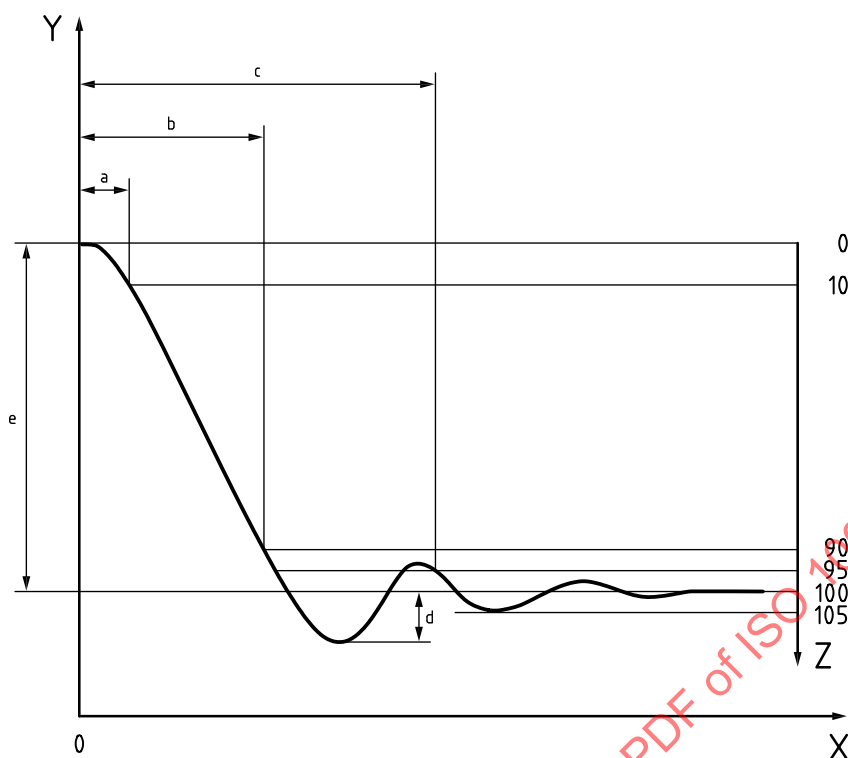
Key	
X	time, in s
Y	outlet tank pressure change, in kPa
Z	change in pressure, in % of total change in pressure
a	Shifting time.
b	Response time.
c	Settling time.
d	Overshoot, in % of total change in pressure.
e	Total change in pressure, in kPa.

Figure 11 — Determination of charge characteristics from pressure response

Report these values corresponding to charge tests as shown in ISO 10094-1:2021, Table 2.

11.3.4 Discharge characteristics

From the discharge characteristics curves obtained in 11.3.2, determine for each control step and for each of the four volumes, the shifting time, the response time, the settling time and the undershoot for intermediary steps as defined in Figure 12.

**Key**

X	time, in s	a	Shifting time.
Y	outlet tank pressure change, in kPa	b	Response time.
Z	change in pressure, in % of total change in pressure	c	Settling time.
		d	Overshoot, in % of total change in pressure.
		e	Total change in pressure, in kPa.

Figure 12 — Determination of discharge characteristics

Report these values corresponding to discharge tests as shown in ISO 10094-1:2021, Table 2.

12 Presentation of test results**12.1 General**

Data from which the performances of the electro-pneumatic continuous pressure control valve can be compared shall be presented as described in the following subclauses.

12.2 Control signal/pressure static characteristics

The static control-pressure characteristics, determined according to 7.3, shall be presented as follows:

- a data graph in accordance with ISO 10094-1:2021, Figure 1;
- the value of the linearity obtained according to Formula (1);
- the hysteresis value obtained according to Formula (2);
- the minimum regulated pressure value obtained according to 7.3.4;
- the resolution value obtained according to 7.3.5;

- the repeatability value obtained according to [Formula \(4\)](#);
- the sensitivity value obtained according to [Formula \(5\)](#);
- the offset value obtained according to [Formula \(6\)](#).

12.3 Flow rate/pressure characteristics

The static flow rate/pressure characteristics, determined according to [8.3](#), shall be presented as follows:

- a data graph in accordance with ISO 10094-1:2021, Figure 3;
- the hysteresis value obtained according to [8.4.2](#);
- the value of the maximum forward sonic conductance according to [Formula \(7\)](#);
- the value of the maximum relief sonic conductance according to [8.4.4](#).

12.4 Pressure regulation characteristics

The static pressure regulation characteristics, determined according to [Clause 9](#), shall be presented as follows:

- a data graph in accordance with ISO 10094-1:2021, Figure 4.

12.5 Leakage characteristic

The static characteristic of the leakage at null forward flow rate or relief flow rate, determined according to [Clause 10](#), shall be presented as follows:

- the maximal value of the leakage, according to [10.3](#).

12.6 Dynamic characteristics

The dynamic characteristics, determined according to [Clause 11](#), shall be presented as follows:

- a graph of time dependent curves of the evolution of the pressure in the volume during the charge of the tanks, in accordance with ISO 10094-1:2021, Figure 5;
- a graph of time dependent curves of the evolution of the pressure in the volume during the discharge of the tanks, in accordance with ISO 10094-1:2021, Figure 6;
- a table of charge and discharge characteristic values, in accordance with ISO 10094-1:2021, Table 2.

NOTE For presentation of test results of frequency characteristics, see [A.5](#).

Annex A (informative)

Frequency responses

A.1 Test installation

The test circuit for frequency characterization is the same as for step responses. It is shown in [Figure 10](#). It is built according to the recommendations of [11.1](#).

The test tank volumes are chosen from [Table 2](#).

A.2 Test procedure

A.2.1 According to the port size of the pressure control valve under test, choose a tank with a volume that corresponds to one of those of [Table 2](#).

A.2.2 Install the continuous pressure control valve according to [Figure 10](#), without flow. Apply the inlet pressure, p_1 , chosen according to [5.3.2](#).

A.2.3 Generate a sinusoidal control signal around 50 % of the maximum regulated pressure with an amplitude of 10 % of its full scale (thus varying from 45 % to 55 %), with a low frequency of 0,1 Hz. Simultaneously record the evolution of the control signal and the evolution of the measured pressure at tank level. If necessary, adjust the value of the control signal central value to obtain pressure oscillations between two constant values. If 0,1 Hz is too high, the initial value of frequency may be reduced to a lower value.

A.2.4 Determine the amplitude characteristic in decibels and the phase lag characteristic in degrees of the pressure signal at tank level compared to the set point signal given by the control signal. [Annex B](#) illustrates way to read these data and describes the calculation method because response curves can sometimes be to fairly non-linear.

A.2.5 Progressively increase the frequency of the control signal, while maintaining its amplitude constant.

A.2.6 For each frequency, record the amplitude characteristic of the tank pressure and its phase lag versus the control signal. Record especially for the frequencies corresponding respectively to:

- an attenuation of 3 dB (amplitude ratio equal to 0,7), and
- a phase lag of 90°.

A.2.7 Repeat test procedures [A.2.5](#) and [A.2.6](#) for around 15 different frequencies until an attenuation of 15 dB is reached (amplitude ratio equal to 0,18).

A.2.8 Repeat procedures [A.2.4](#) to [A.2.7](#) for sinusoidal control signals around 50 % of the maximum regulated pressure with amplitudes of 50 % (25 % to 75 %) and 90 % (5 % to 95 %) from a low frequency of 0,1 Hz. If necessary, adjust the value of the control signal central value in order to obtain pressure oscillations between two constant values.

A.2.9 Repeat procedures [A.2.2](#) to [A.2.8](#) for the three other test tank volume values of [Table 2](#).